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WE CLAIM:

a supply a converte the supply and has the direction; a plane supply and the converte		
a converted the supply and has the direction; a plane supply and the co	apparatus comprising:	
the supply and has the direction; a plane supply and the co	ly holding a flattened box blank;	
the direction; a plane supply and the co	eyor passing in a transport direction adjacent	
a plane supply and the co	aving a succession of box seats spaced apart in	
supply and the co		
*	et carrier rotatable about a sun axis between th	36
a sincl	onveyor;	
3-	le planetary element on the carrier offset from	
the sun axis, have	ving axially spaced inner and outer ends, and	
10 rotatable about a	a planet axis parallel to and offset from the su	m
n axis;		
12 a grab	on the planetary-element outer end engageable	
with the blank in	the supply and engageable in the conveyor	
14 seats;		
a plane	at drive wheel fixed to the planetary-element	
inner end and rot	tatable with the planetary element about the	,
planet axis;		
a sun w	wheel rotatable about the sun axis;	;
19 means c	coupling the wheels together for joint	
20 synchronous rotat		
21 carrier	cion;	
22 rotating the carr	cion; drive means connected to the carrier for	

element orbits about the sun axis; and

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planetary drive means separate from the carrier driv means and connected to the sun wheel for rotating the planetary element about the planet axis independently of the carrier such that the grab moves while orbiting about the sun axis through a closed asymmetric path having only two outer points, the grab engaging the blank in the supply in one of the outer points and pr ssing the blank into one of the seats in the other of the outer points.

- The apparatus defined in claim 1 wherein the planetary drive means includes a stepping motor.
- 3. The apparatus defined in claim 1 wherein the 1 planetary drive means includes a servomotor.
- 4. The apparatus defined in claim 3 wherein the 1 servomotor steps the planetary element angularly about the planet 2 axis. 3
- The apparatus defined in claim 1 wherein the 1 planetary drive means orients the grab relative to the planet axis at about 120 offset positions in th outer points. 3

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- 6. The apparatus defined in claim 1 wherein the
 conveyor is provided with leading uprights movable in the
 direction and sliding uprights movable relative to the leading
- uprights, each cell having one of the leading uprights and one of
- the sliding uprights.
- 7. The apparatus defined in claim 1 wherein the
 planetary drive means is of variable speed but always rotates the
 planetary element in the same rotational sense.
- 8. The apparatus defined in claim 1 wherein the
 carrier drive means rotates the carrier in a rotational sense
 opposite that of a rotational sense imparted to the planetary
 element by the planetary drive.
- 9. The apparatus defined in claim 1 wherein the supply is a downwardly inclined chute.

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- 10. The apparatus defin d in claim 1 wherein the
- element is L-shaped and has a main leg extending along the
- planetary axis and a transverse leg extending generally
- perpendicular from the main leg and having the outer end carrying
- the grab.